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Introduction

Introduction

Driver Monitoring Systems

Modern *driver monitoring systems* (DMSs) in Level-2+ self-driving-enabled cars aim to enhance safety by estimating drivers' readiness levels for driving and enabling safe control handovers when necessary.

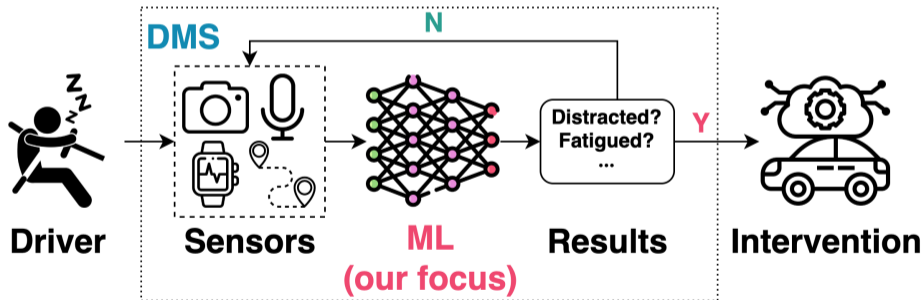


Fig. 1: A simplified illustration of a DMS.

These systems usually rely various sensors, which may be deployed at different in-car locations, to comprehensively monitor drivers' states, e.g.,

- ▶ **RGB**: optical details.
- ▶ **Depth**: 3D information.
- ▶ **Infrared**: thermal information.
- ▶ **ECG**: heart rates.
- ▶ **Audio**: speech and sound.

Hence, modern DMSs are *multimodal* (and *multiview*).

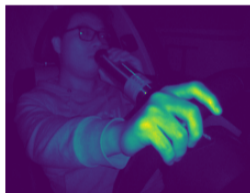
Our work specifically focuses on *driver action recognition*, which involves classifying drivers' actions into *normal driving* and several *non-driving-related activities* (NDRAs), e.g., texting and drinking.



(a) Top IR



(b) Top Depth



(c) Front IR



(d) Front Depth

Fig. 2: Sample frames from the DAD dataset [1].

Our contributions in this paper are as follows:

1. We propose a novel robust *multiview multimodal* DMS for driver action recognition that leverages feature-level fusion through masked *multi-head self-attention* (**MHSA**).
2. We manually annotated the anomalies in DAD dataset with 9 fine-grained classes of non-driving-related activities (NDRAs).
3. We conduct extensive experiments on the DAD dataset to compare different fusion strategies, assess the significance of individual views/modalities, and evaluate the efficacy of patch masking in enhancing MHSA's robustness against view/modality collapses. Results show that our MHSA-based DMS achieves state-of-the-art performance with an AUC-ROC score of 97.0%.

Related Work

Related Work

Driver Monitoring Datasets

- ▶ AUC-DD [2] is the first public dataset for DMSs. It was collected using an RGB camera from a single side view and thus have some limitations.



Fig. 3: A sample from the AUC-DD dataset [2] illustrating that RGB is not robust to illumination changes.

- ▶ Later databases [1], [3]–[5] have incorporated additional views and modalities to address these issues.
 - ▶ For example, top and front views have also been introduced to capture the driver's hand and head movements amongst other movements.
 - ▶ Regarding modalities, IR and depth have also become popular, as they can provide thermally based features and geometry information, which are complementary to the optical details from RGB.
- ▶ Among these datasets, we benchmark our models on DAD [1], the only one designed for SAE L2+ with open-set recognition: its test set contains extra classes of NDRAs in addition to those in the training split.

Various multiview multimodal DMSs have also been proposed with different emphases:

- ▶ Kopuklu *et al.* [1] proposed a novel learning framework based on contrastive learning.
- ▶ Ortega *et al.* [4] and Su *et al.* [6] proposed to leverage Conv-LSTM structures.
- ▶ Only Shan *et al.* [7] proposed a feature-level modality fusion method, but it has several drawback:
 - ▶ Features are pooled before fusion, which leads to the loss of semantic information.
 - ▶ Its fusion module has the additional task of handling the temporal dimension.

Thanks!

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